

MeO Laser Ranging Station

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Observatoire
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OCA Laser ranging New Organization

Until 2003 the French laser ranging activity was represented by 3 tracking laser stations

CERGA

Lunar Laser Ranging
(LLR)

for the Moon and high
altitude satellites

Satellite Laser
Ranging (SLR)

for low altitude
satellites

Transportable Laser
Ranging System
(FTLRS)

for mobile campaigns

OCA Laser ranging New Organization

Since 2004 and 2008 a new organisation has been setup to initiate, in addition to the last program, an instrumental Research and Development activity

GEOAZUR

transportable Laser Ranging
System (FTLRS)
for mobile campaigns

MeO Station
(Ex LLR)

for the Moon and both high and
low altitude satellites
Research and Development



MeO Station

● Objectives

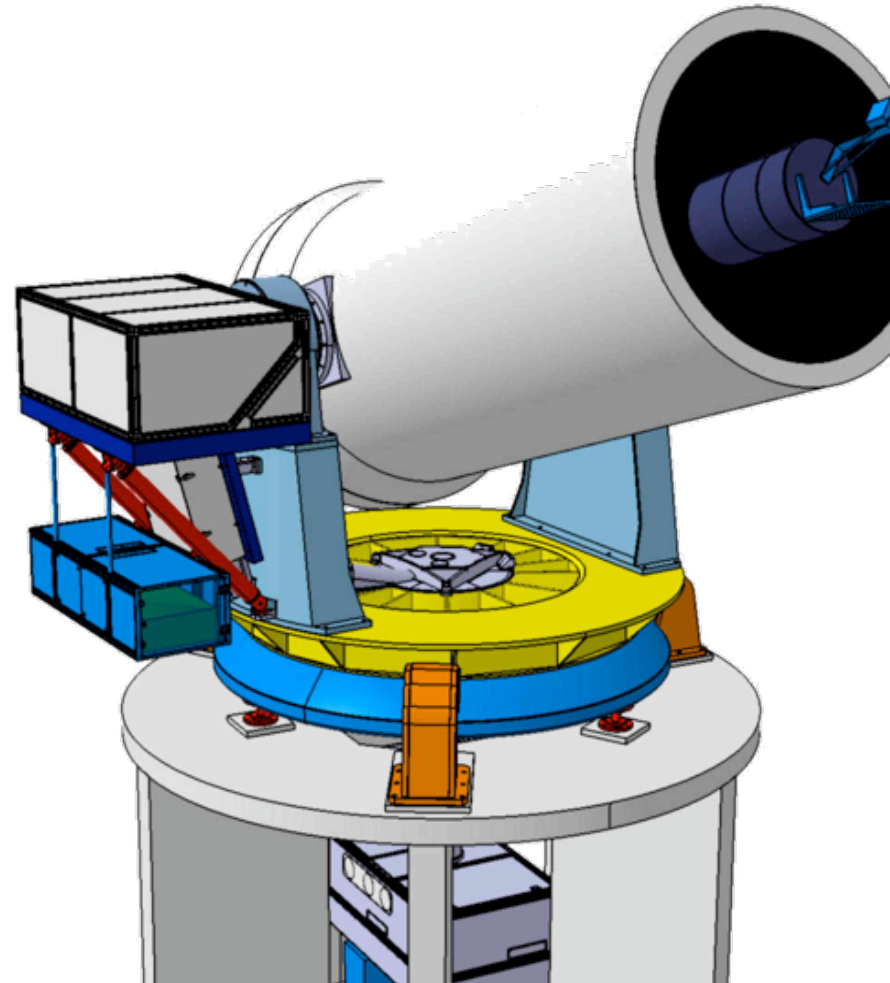
- » Increase the capability of the station
 - » From 400 km to the Moon (speed)
 - » One way interplanetary mission (accuracy)
- » Give the possibility to do Instrumental research (laboratories facilities)
- » Improve the automation

● Instrumental Developments

- » Transformation of the space to build laboratories
- » Replacement of the motorization of the telescope for speed and accuracy
- » Renovation of the dome for speed
- » Laser and coudé
- » Control Software
- »

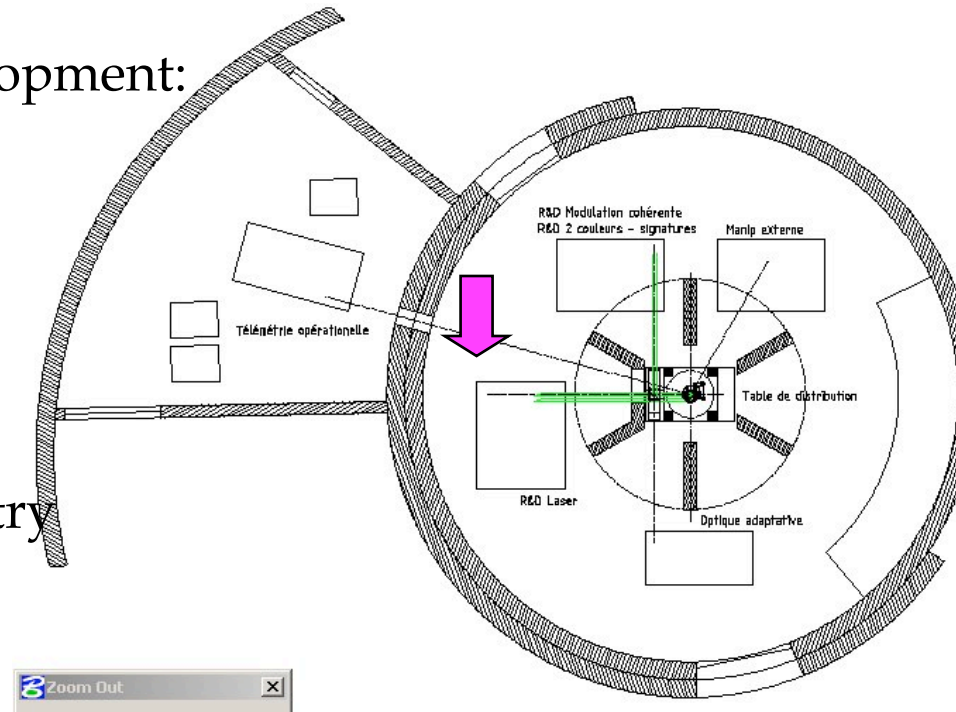
MeO Station from 400 km to the moon

- Ritchey Chretien configuration
 - » Primary Mirror: Parabolic 1540 mm
 - » Nasmyth table
- AltAz mount
- Common Telescope
 - » Laser emission
 - » Detection
 - » Video

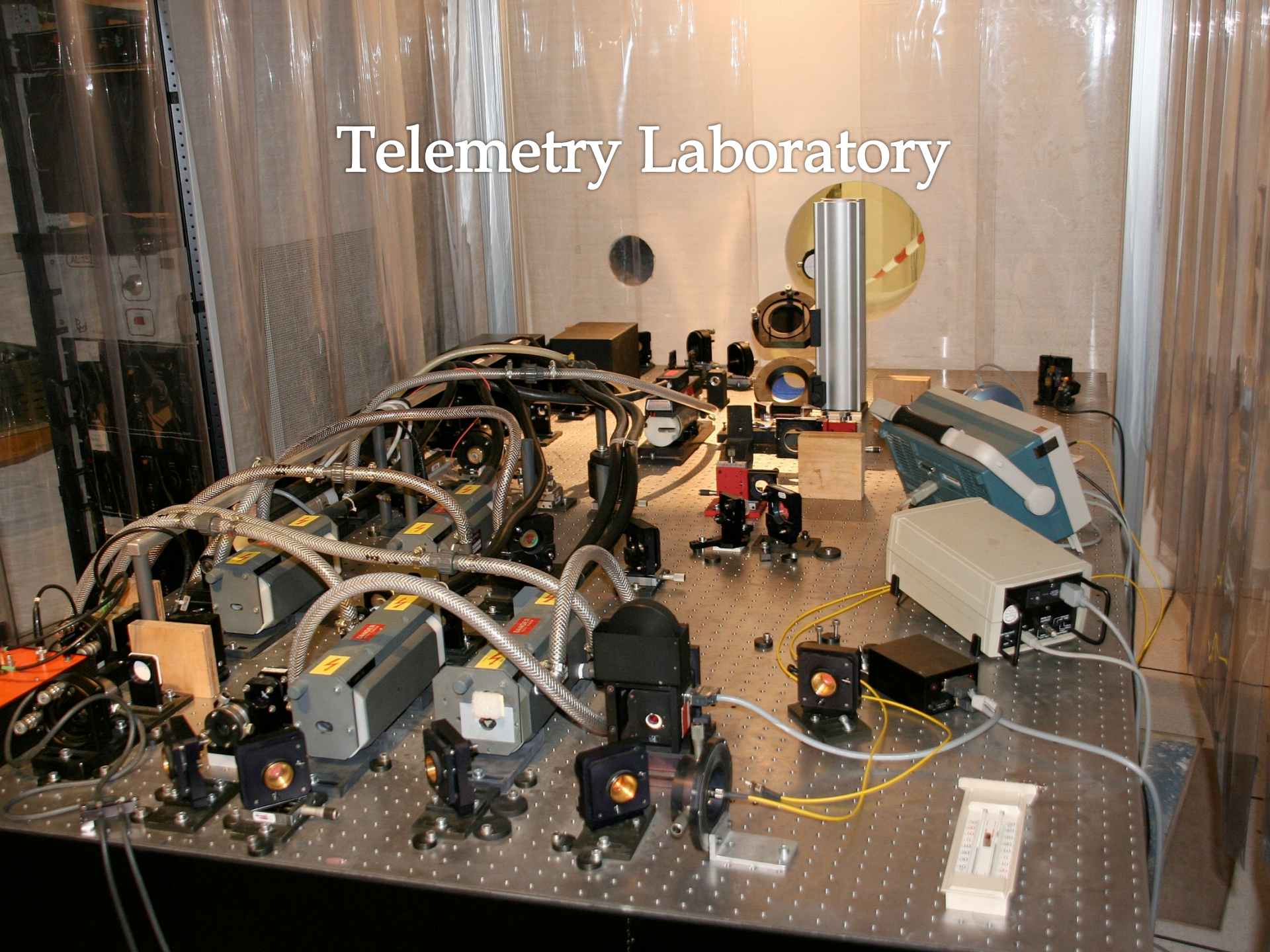


Focus laboratories

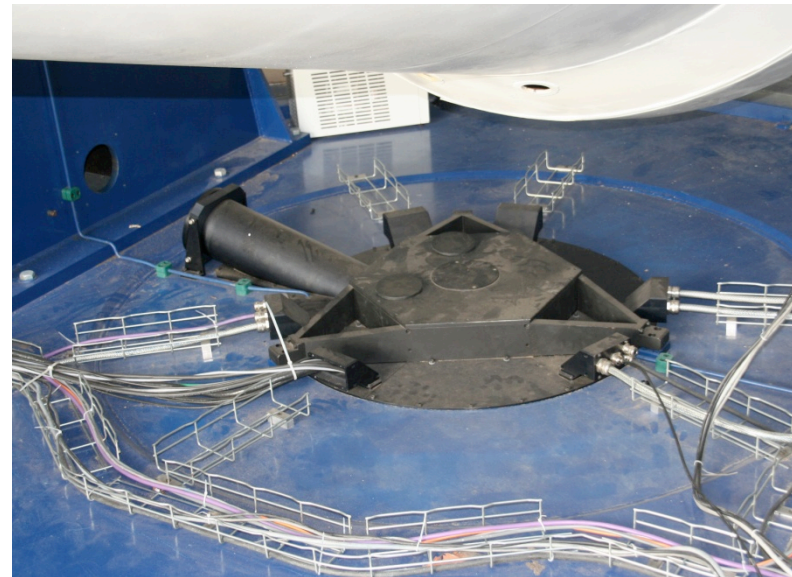
- Built 2 new laboratories in direct connection with the telescope flux
- laboratory for research and development:
 - » Circular room: 60 m²,
 - » 4 optical benches
 - » 1 optical bench for the optical flux distribution
- laboratory for operational telemetry
 - » 6 m apart from the telescope: 45 m²
 - » 1 optical bench for the laser and the detection unit



Telemetry Laboratory



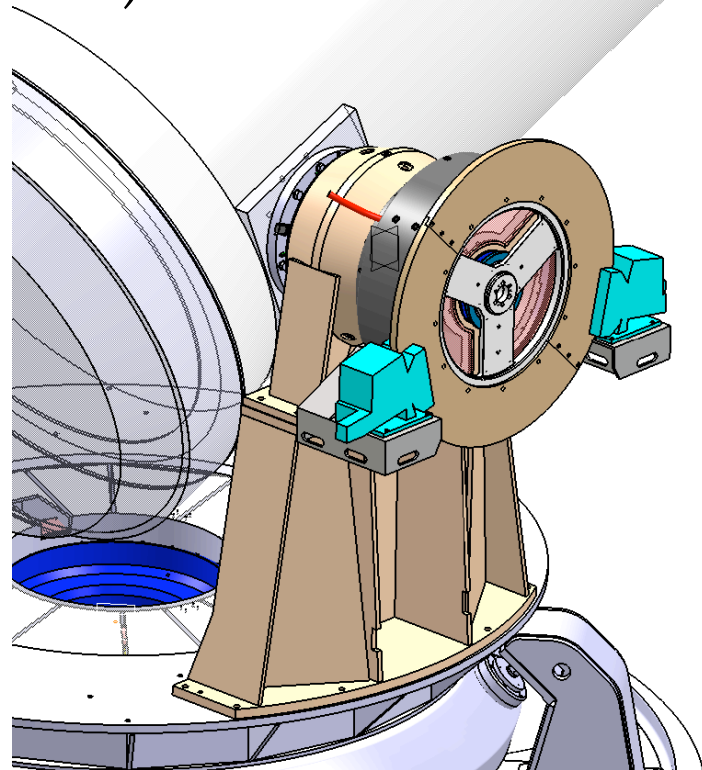
Fold mirrors



Telescope motorization

Speed and acceleration

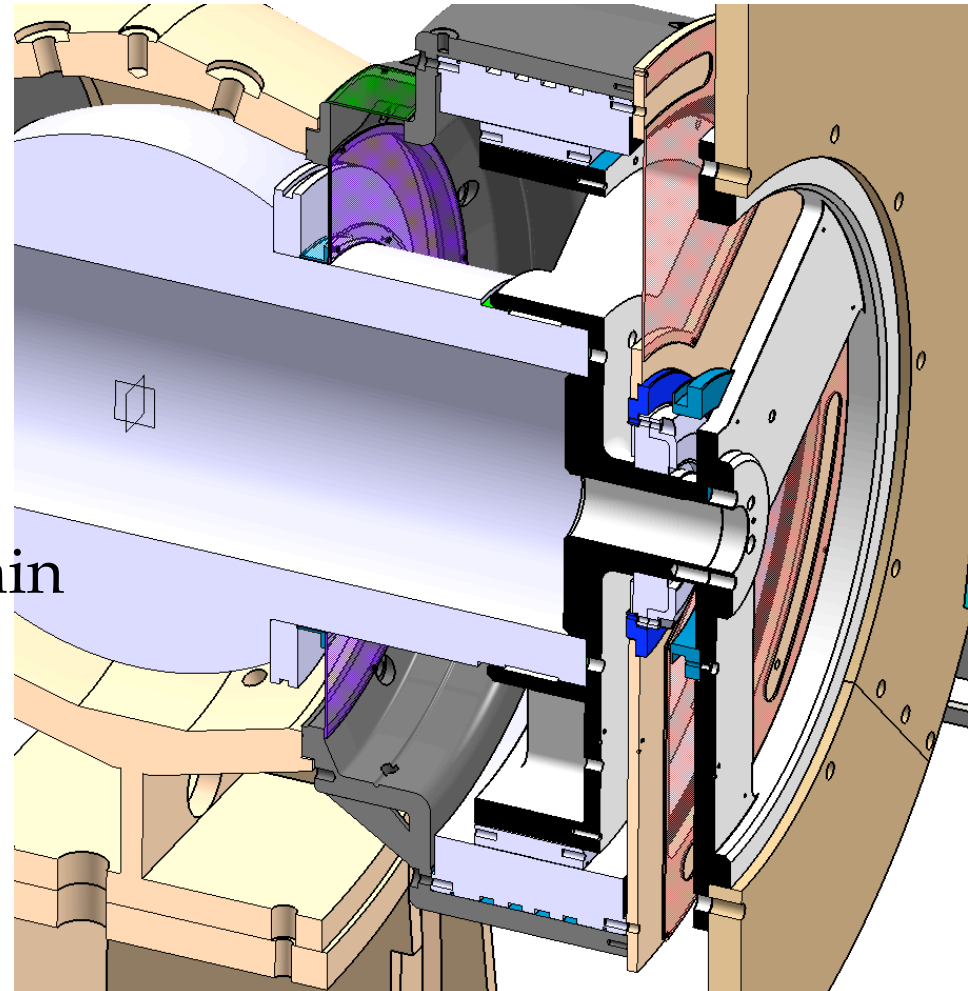
- Increase the speed of the telescope to be able to track low altitude satellite (400 km)
 - » speed: $5^\circ/\text{s}$
 - » acceleration: $1^\circ/\text{s}^2$
 - » Dôme speed: $v = 5^\circ/\text{s}$



New motorization

Elevation axe

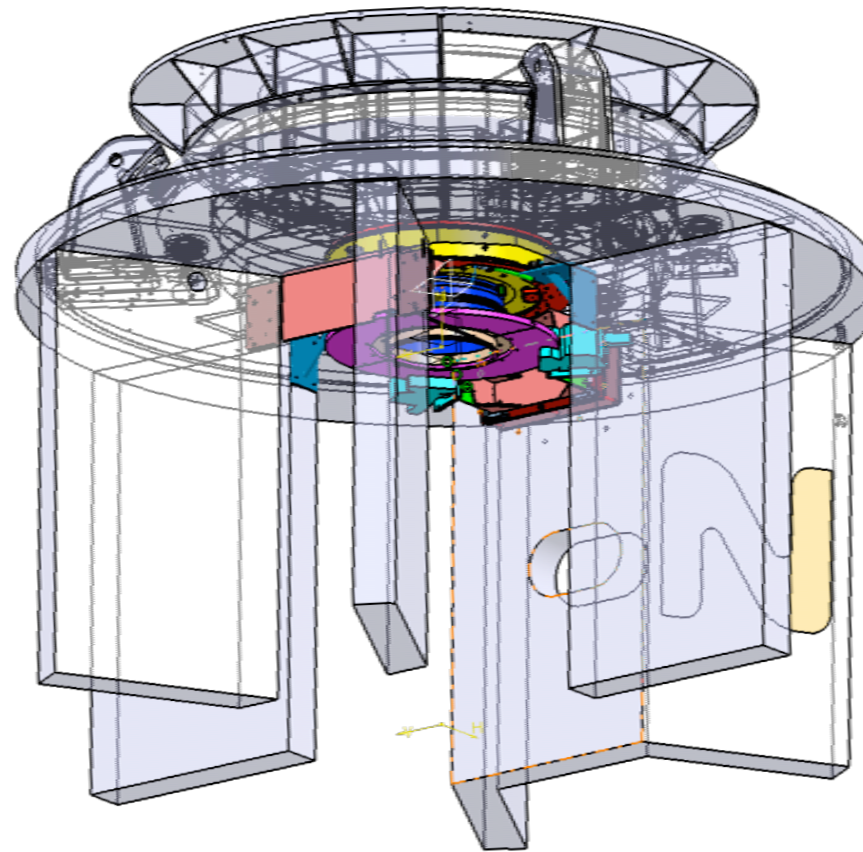
- Direct drive Etel motor
 - » Torque: 1000 kg.m
 - » Diameter 800 mm
- DSPC2 drive (Etel)
 - » Encoder integrator
 - » Power module
 - » Computation system
- Absolute encoder Heidenhain
 - » Linearity : 1 arcsec
 - » Precision : 0.01 arcsec
- Brake
 - » Parking
 - » Security





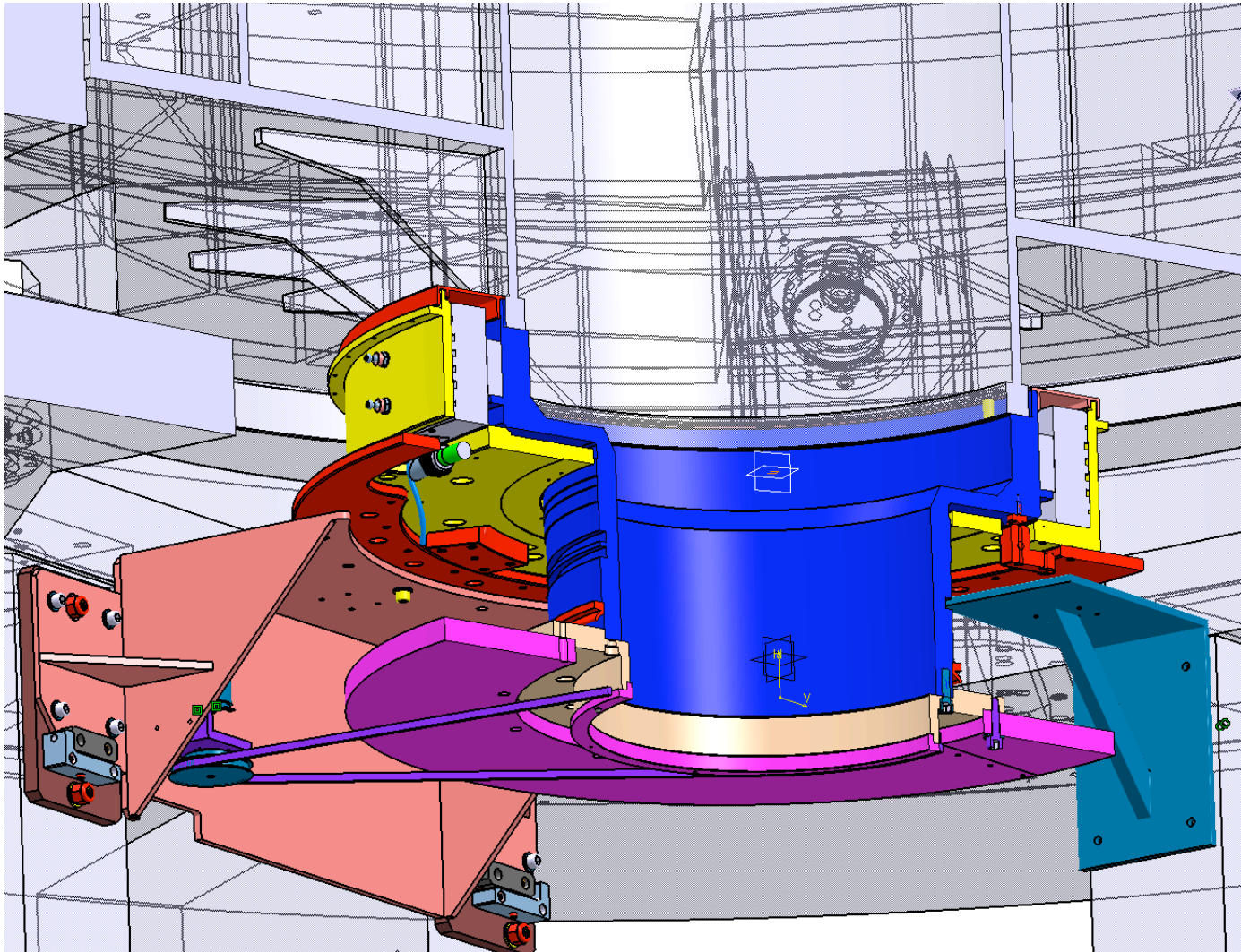
New motorization vertical axe

- Direct drive Etel
 - » Torque: 1000 kg/m
 - » Diameter: 1000 mm - 600 mm
- DSPC2 drive (Etel)
 - » Encoder integrator
 - » Power module
 - » Computation
- Incremental tape encoder Heidenhain
 - » Linearity : 20 arcsec
 - » Precision : 0.01 arcsec
- Brake
 - » Parking
 - » Security

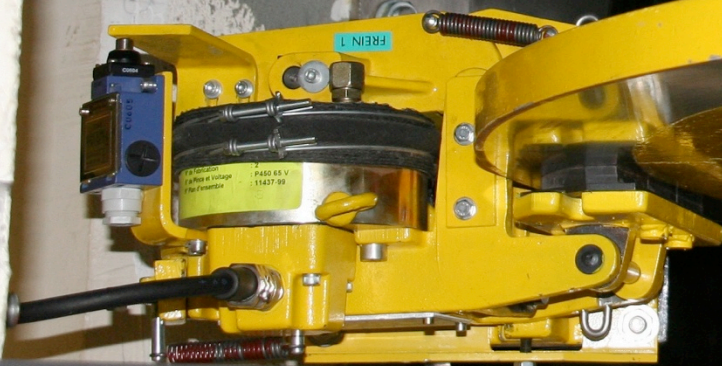


New motorization

Direct drive and direct encoder



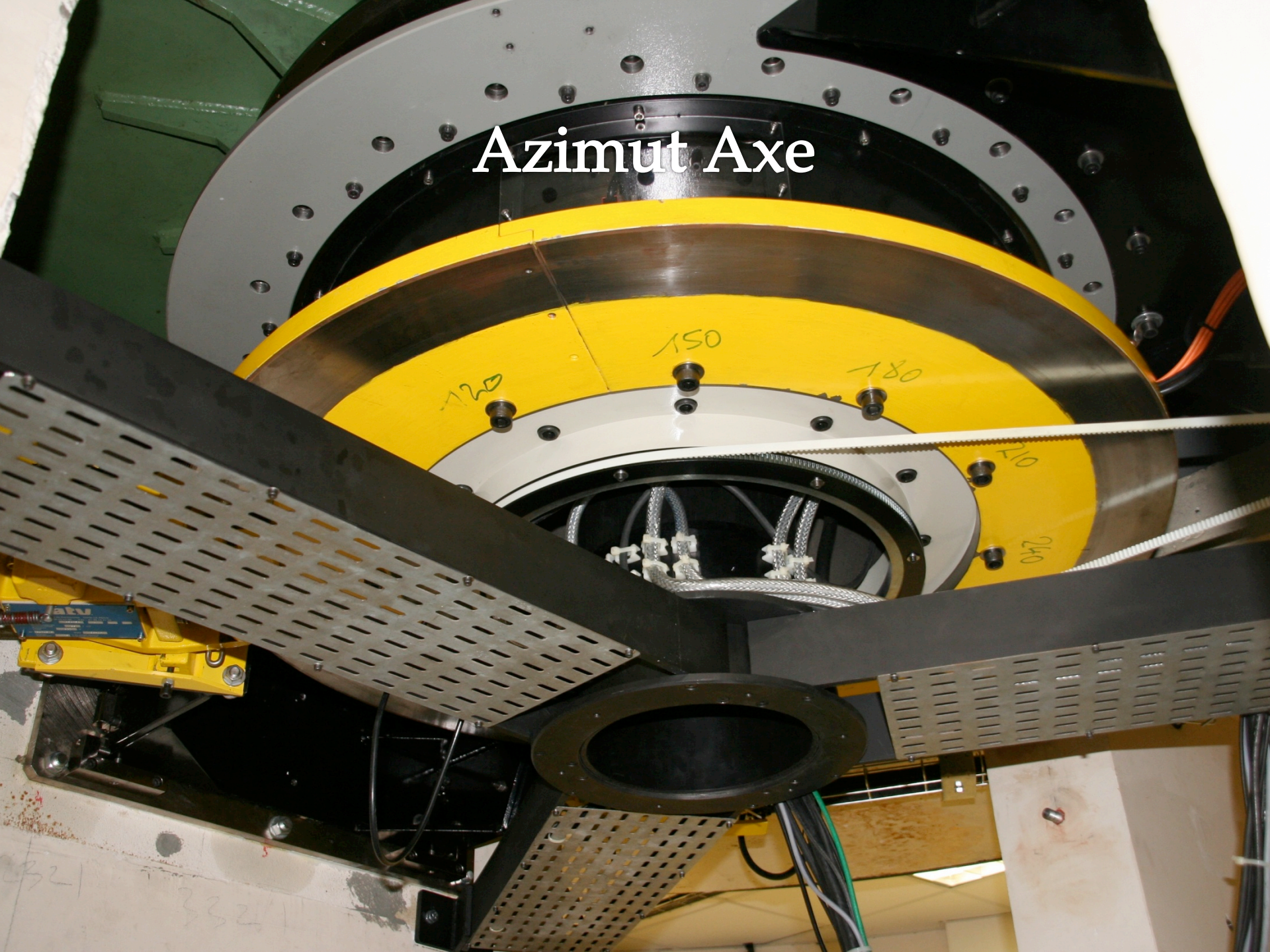
Azimut Axe



FREIN 1

1. Révision 2
2. Révisé le 14/02/99
3. Révisé par 1407/99

Azimut Axe



Dome



Status

- First light of the telescope in the new configuration:
May 2008
- First echoes obtained in July 2008
- Continuous observation will start by the end of
October
- Ranging the moon in November

Conclusions

- The capability of the station is now extended from low altitude satellite to the moon or spacecraft in the solar system
- The Moon will continue to be a major objective for the station together with Time transfer and high altitude satellite
- The new configuration of the station will permit to perform both laser ranging and experimental research